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# GENERALIZED CONTRACTING MAPPING ON M<sub>b</sub>-METRIC SPACES WITH APPLICATION

Neeraj Malviya<sup>1</sup> Jerolina Fernandez<sup>2\*</sup> and Sheela<sup>3</sup>

<sup>1</sup>Department of Mathematics, Govt. Degree College Timarni, Harda, M.P., India

<sup>2,3</sup>Department of Science, The Bhopal School of Social Sciences, Bhopal, M.P., India *Email: jerolinafernandez@gmail.com* 

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"together we can and we will make a difference"

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# GENERALIZED CONTRACTING MAPPING ON Mb-METRIC SPACES WITH APPLICATION

Neeraj Malviya<sup>1</sup> Jerolina Fernandez<sup>2\*</sup> and Sheela<sup>3</sup>

<sup>1</sup>Department of Mathematics, Govt. Degree College Timarni, Harda, M.P., India

<sup>2,3</sup>Department of Science, The Bhopal School of Social Sciences, Bhopal, M.P., India

Email: jerolinafernandez@gmail.com

# ABSTRACT

In the present paper, we establish some fixed point theorems in the framework of  $M_b$ -metric space. As illustrations few examples are presented. Finally, as application, we discuss the existence of non-linear integral equation solution. **Mathematics Subject Classification (2000):** 47H10.

*Keywords:* Mapping, theorem, non-linear, equation, generalized contraction mapping etc.

# **INTRODUCTION**

As a generalization of metric space, in 1989, Bakhtin [2] (and Czerwik [3], 1993) derived a number of theorems of fixed points in the form of partial metric spaces. In 1994, Matthews [13] introduced the concept of partial metric space. This extension of metric states that the distance between a point and itself is not zero. The theory of the metric fixed point has been generalised by several researchers in different directions. (see [4-7, 9-12]).

Asadi et al. [1] in 2014 introduced M-metric space, the generalization of partial metric space and produced some fixed-point results on generalized contractions.  $M_b$ -metric space was introduced in 2016 (Mlaiki et al., 2016) [14]. This structure is an extension of partial metric space and yields some fixed-point Theorems.

In light of the same spirit, the aim of this paper, is to define generalized contraction map in order to examine the existence of a fixed point for this mapping, in  $M_b$  -metric space. In the current literature, our results have extended significantly a number of well documented findings.

## 2. Preliminaries

Let's start by reviewing the following notation: **Notation 2.1** [1]

 $1.m_{\mu,\sigma} = \min \{m(\mu,\mu), m(\sigma,\sigma)\}$ 

 $2.M_{\mu,\sigma} = \max\left\{m(\mu,\mu),m(\sigma,\sigma)\right\}$ 

**Definition 2.2.** [1] Let  $\varphi$  be a nonempty set. Suppose  $m: \varphi^2 \to R^+$  satisfies

$$(m1) \ m(\mu, \ \mu) = m(\sigma, \ \sigma) = m(\mu, \ \sigma)$$
 if and only if  $\mu = \sigma$ ,

 $(m2) \ m_{\mu,\sigma} \le m(\mu, \sigma),$   $(m3) \ m(\mu, \sigma) = m(\sigma, \mu),$  $(m4) \ (m(\mu, \sigma) - m_{\mu,\sigma}) \le (m(\mu, \omega) - m_{\mu,\sigma})$ 

 $m_{\mu,\omega}$ ) + ( $m(\omega, \sigma) - m\omega,\sigma$ ) for all  $\mu, \sigma, \omega \in \varphi$ . Then

 $(\varphi, m)$  is called an M-metric space.

The concept of  $M_b$ -metric space was given by Mlaiki et al. [14], but first we review the following notation.

Notation 2.3. [14]

(1)  $m_{b_{\mu,\sigma}} = \min\{m_b(\mu,\mu), m_b(\sigma,\sigma)\}$ 

(2)  $M_{b_{\mu,\sigma}} = max\{m_b(\mu,\mu), m_b(\sigma,\sigma)\}$ 

**Definition 2.4.** [14] Let  $\varphi$  be a nonempty set. Suppose  $m_b: \varphi^2 \to R^+$  satisfies

 $(m_b 1) m_b(\mu, \mu) = m_b(\sigma, \sigma) = m_b(\mu, \sigma)$  if and only if  $\mu = \sigma$ ,

 $(m_b 2) m_{b_{\mu,\sigma}} \leq m_b (\mu, \sigma),$ 

 $(m_h 3) m_h (\mu, \sigma) = m_h(\sigma, \mu),$ 

$$(m_b 4) (m_b(\mu, \sigma) - m_{b_{\mu,\sigma}}) \leq s[(m_b(\mu, \omega) - m_{b_{\mu,\sigma}})] \leq s[(m_b(\mu, \omega) - m_{b_{\mu,\sigma}})]$$

 $m_{b_{\mu,\omega}}) + (m_b(\omega, \sigma) - m_{b_{\omega,\sigma}})] - m_b(\omega, \omega).$ 

for all  $\mu, \sigma, \omega \in \varphi$ , where  $s \ge 1$ , then  $(\varphi, m_b)$  is called an  $M_b$ -metric space.

**Example 2.5.** Let  $\varphi = [0, \infty)$  and  $m_b$ :  $\varphi^2 \rightarrow \mathbb{R}^+$ , for all  $\mu, \sigma \in \varphi$  we have

$$m_b(\mu, \sigma) = |\mu - \sigma|^2 + \left(\frac{\mu + \sigma}{4}\right)^2.$$

Note that  $(\varphi, m_b)$  is an  $M_b$ -metric space with s = 2, but it is not *M*-metric space since the triangle inequality is not satisfied.

**Example 2.6.** Let  $\varphi = [0, \infty)$  and  $m_b : \varphi^2 \rightarrow \mathbb{R}^+$ , for all  $\mu, \sigma \in \varphi$  we have

$$n_b(\mu, \sigma) = |\mu - \sigma|^2 + 3.$$

Note that  $(\varphi, m_b)$  is an  $M_b$ -metric space with s = 2, but it is not a cone b-metric space over Banach algebra A since for and  $\mu > 0$ , we have  $m_b(\mu, \mu) \neq 0$ .

**Example 2.7.** Let  $\varphi = [0, \infty)$  and  $m_b : \varphi^2 \rightarrow \mathbb{R}^+$ , for all  $\mu, \sigma \in \varphi$  we have

 $m_b(\mu, \sigma) = (max\{\mu, \sigma\})^2.$ 

Note that  $(\varphi, m_b)$  is an  $M_b$ -metric space with s = 2, but it is not *M*-metric space since the triangle inequality is not satisfied.

**Example 2.8.**[14] Let  $\varphi = [0, \infty)$  and l > 1 be constant and  $m_b: \varphi^2 \to [0, \infty)$  defined for all  $\mu, \sigma \in \varphi$  we have

 $m_b(\mu, \sigma) = max \{\mu, \sigma\}^l + |\mu - \sigma|^l$ . Note that  $(\varphi, m_b)$  is an  $M_b$ -metric with  $s = 2^l$ , but it is not M-metric space since the triangle inequality is not satisfied.

#### 3. Topology for $M_b$ -metric space

**Definition 3.1.** [14] Let  $(\varphi, m_b)$  be an  $M_b$ metric space with  $s \ge 1$ . Then, for all  $x \in \varphi$  and  $\varepsilon > 0$ , the open ball with centre  $\mu$  and radius  $\varepsilon$  is defined by

 $B_{m_b}(\mu,\varepsilon) = \{ \sigma \in \varphi : m_b(\mu,\sigma) < m_{b_{\mu,\sigma}} + \varepsilon \}.$ 

**Definition 3.2.** Let  $(\varphi, m_b)$  be an  $M_b$ -metric space with  $s \ge 1$ . Each  $M_b$ -metric generates a topology  $\tau_{m_b}$  on  $\varphi$  whose base is the family of open  $m_b$ -balls  $\{B_{m_b}(\mu, \varepsilon): \mu \in \varphi, \varepsilon > 0\}$ , where  $B_{m_b}(\mu, \varepsilon) = \{\sigma \in \varphi: m_b(\mu, \sigma) - m_{b_{\mu,\sigma}} < \varepsilon\}.$ 

**Proposition 3.3.** An  $M_b$ -metric space is a  $T_0$ -space.

**Proof:** Let  $(\varphi, \tau_{m_b})$  be an  $M_b$ -metric space and  $\mu, \sigma \in \varphi$  such that  $\mu \neq \sigma$ . Then from  $(m_b 2)$ , we have

$$m_{b_{\mu,\sigma}} \leq m_b(\mu,\sigma) \Rightarrow$$

$$\min\{m_b(\mu,\mu),m_b(\sigma,\sigma)\} \le m_b(\mu,\sigma),$$

That is,

 $m_b(\mu,\mu) \le m_b(\mu,\sigma) \text{ or } m_b(\sigma,\sigma) \le m_b(\mu,\sigma).$ Firstly, assume that  $m_b(\mu,\mu) = m_b(\sigma,\sigma)$ . Then we have

$$m_{b_{\mu,\sigma}} = m_b(\mu,\mu)$$
  
=  $m_b(\sigma,\sigma)$   
<  $m_b(\mu,\sigma)$ .

Yielding  $m_b(\mu, \sigma) - m_{b_{\mu,\sigma}} = m_b(\mu, \sigma) - m_{b_{\mu,\sigma}}$ 

 $m_b(\mu,\mu)>0.$ 

If we choose  $\varepsilon > 0$  such that  $m_b(\mu, \sigma) - m_b(\mu, \mu) = \varepsilon$  then  $m_b(\mu, \sigma) < m_{b_{\mu,\sigma}} + \varepsilon$ , so that

 $\sigma \notin B_{m_b}(\mu, \varepsilon)$ . Next, assume that  $m_b(\mu, \mu) < m_b(\sigma, \sigma)$ . Then

$$m_{b_{\mu,\sigma}} = m_b(\mu, \mu)$$
  

$$< m_b(\mu, \sigma),$$
  

$$\Rightarrow m_b(\mu, \sigma) - m_{b_{\mu,\sigma}}$$
  

$$= m_b(\mu, \sigma)$$
  

$$- m_b(\mu, \mu) > 0.$$

Again, if we choose  $\varepsilon > 0$  such that  $m_b(\mu, \sigma) - m_b(\mu, \mu) = \varepsilon$ , then  $m_b(\mu, \sigma) < m_{b_{\mu,\sigma}} + \varepsilon$ , so that  $\sigma \notin B_{m_b}(\mu, \varepsilon)$ .

Similarly, for  $m_b(\mu,\mu) > m_b(\sigma,\sigma)$ , one can easily show that  $\mu \in B_{m_b}(\mu,\varepsilon)$  and  $\sigma \notin B_{m_b}(\mu,\varepsilon)$ . Therefore, for any two distinct points  $\mu, \sigma \in \varphi$ , there is a ball containing one and not containing the other point. Hence  $(\varphi, m_b)$  is a  $T_0$ -space.

We now discuss the definitions of convergence in  $M_b$ -metric space.

**Definition 3.4.**[14-15] Let  $(\varphi, m_b)$  be a  $M_b$ -metric space. Then:

1) A sequence  $\{\mu_n\}$  in  $\varphi$  converges to a point  $\mu$  if and only if

$$\lim_{m \to \infty} m_b(\mu_n, \mu_m) - m_{b_{\mu_n, \mu_n}}$$

2) A sequence  $\{\mu_n\}$  in  $\varphi$  is said to be  $M_b$ -Cauchy sequence if and only if

$$\lim_{\substack{n,m\to\infty}} (m_b(\mu_n,\mu_m) - m_{b_{\mu_n,\mu_m}}) \text{ and}$$
$$\lim_{\substack{t,m\to\infty}} (M_{b_{\mu_n,\mu_m}} - m_{b_{\mu_n,\mu_m}}) \text{ exists and finite.}$$

3) An  $M_b$  -metric space is said to be complete if every  $M_b$ -Cauchy sequence  $\{\mu_n\}$ converges to a point  $\mu$  such that

$$\lim_{n,m\to\infty} m_b(\mu_n,\mu_m) - m_{b_{\mu_n,\mu_m}} = 0 \text{ and}$$
$$\lim_{n,m\to\infty} M_{b_{\mu_n,\mu_m}} - m_{b_{\mu_n,\mu_m}} = 0.$$

### MAIN RESULTS

We now state our main results.

**Theorem 4.1:** Let  $(\varphi, m_b)$  be a complete  $M_b$ metric space with  $s \ge 1$  and  $\xi: \varphi \to \varphi$  satisfying the condition:

$$(4.1) \qquad m_b(\xi\mu,\xi\sigma) \le \alpha m_b(\mu,\sigma) + \\ \beta m_b(\mu,\xi\mu) + \gamma m_b(\sigma,\xi\sigma)$$

 $\forall \mu, \sigma \in \varphi$ , where  $\alpha, \beta, \gamma, \rho \ge 0$ , with  $\alpha + \beta + \gamma < \frac{1}{s}$ , then  $\xi$  has a unique fixed point u such that  $m_{b}(u, u) = 0$ .

**Proof:** Let  $\mu_0 \in \varphi$  be arbitrary. Consider the sequence  $\{\mu_n\}$  defined by  $\mu_n = \xi^n \mu_0$  and  $m_{b_n} = m_b(\mu_n, \mu_{n+1})$ . Note that if there exists a natural

number *n* such that  $m_{b_n} = 0$ , then  $\mu_n$  is a fixed point of  $\xi$ . So, assume that  $m_{b_n} > 0$ , for  $n \ge 0$ . By (4.1), we have

$$m_{b_n} = m_b(\mu_n, \mu_{n+1}) = m_b(\xi \mu_{n-1}, T\xi)$$
  

$$\leq \alpha m_b(\mu_{n-1}, \mu_n) +$$
  

$$\beta m_b(\mu_{n-1}, \xi \mu_{n-1}) + \gamma m_b(\mu_n, \xi \mu_n)$$
  

$$= \alpha m_b(\mu_{n-1}, \mu_n) + \beta m_b(\mu_{n-1}, \mu_n) +$$
  

$$\gamma m_b(\mu_n, \mu_{n+1})$$

 $= \alpha m_{b_{n-1}} + \beta m_{b_{n-1}} + \gamma m_{b_n}$  $= (\alpha + \beta) m_{b_{n-1}} + \gamma m_{b_n}$ for any  $n \ge 0$ ,  $m_{b_n} \le (\alpha + \beta) m_{b_{n-1}} + \gamma m_{b_n}$ , is himplies  $m \le \alpha m_{b_n}$  where  $\alpha = \frac{\alpha + \beta}{\alpha} \le 1$ 

which implies  $m_{b_n} \leq \rho m_{b_{n-1}}$ , where  $\rho = \frac{\alpha + \beta}{1 - \gamma} < 1$ as  $\alpha + \beta + \gamma < \frac{1}{s}$ . By repeating this process, we get  $m_{b_n} \leq \rho^n m_{b_{n-1}}$ . Thus,  $\lim_{n \to \infty} m_{b_n} = 0$ . By (4.1), for all n, m > 0, we have

$$m_b(\mu_n, \mu_m) = m_b(\xi^n \mu_0, \xi^m \mu_0)$$
  
=  $m_b(\xi \mu_{n-1}, \xi \mu_{m-1})$   
 $\leq \alpha m_b(\mu_{n-1}, \mu_{m-1}) +$   
 $\beta m_b(\mu_{n-1}, \xi \mu_{n-1}) + \gamma m_b(\mu_{m-1}, \xi \mu_{m-1})$   
=  $\alpha m_b(\mu_{n-1}, \mu_{m-1}) +$ 

 $\beta m_b(\mu_{n-1},\mu_n) + \gamma m_b(\mu_{m-1},\mu_m)$ 

Thus, from the above inequality, we deduce that

$$m_b(\mu_n, \mu_m) \le \alpha m_b(\mu_{n-1}, \mu_{m-1})$$
 for all  $n \ge 0$ .

By repeating this process, we get  $m_b(\mu_n, \mu_m) \le \alpha^n m_b(\mu_0, \mu_{m-n})$  for all  $n \ge 0$ . Hence,  $m_b(\mu_n, \mu_m) - m_{b_{\mu_n, \mu_m}} \le \alpha^n [sm_b(\mu_0, \mu_1) + sm_b(\mu_1, \mu_{m-n})]$  $\le \alpha^n [sm_b(\mu_0, \mu_1) + sm_b(\mu_1, \mu_{m-n})]$ 

$$s^{2}m_{b}(\mu_{1},\mu_{2}) + s^{2}m_{b}(\mu_{2},\mu_{m-n})] \leq \alpha^{n}[sm_{b}(\mu_{0},\mu_{1}) + s^{2}m_{b}(\mu_{1},\mu_{2}) + \dots + s^{m-n}m_{b}(\mu_{2m-n-1},\mu_{m-n})] \leq \alpha^{n}sm_{b}(\mu_{0},\mu_{1}) + \alpha^{n}s^{2}m_{b}(\mu_{0},\mu_{1}) + \dots + \alpha^{n}s^{m-n}m_{b}(\mu_{0},\mu_{1}) \leq s\alpha^{n}[1 + s\alpha + (s\alpha)^{2} + \alpha^{n}s^{m-n}m_{b}(\mu_{0},\mu_{1})]$$

 $\cdots$  ] $m_b(\mu_0, \mu_1)$ 

$$=\frac{s\alpha^n}{1-s\alpha}m_b(\mu_0,\mu_1)$$

As  $\alpha < \frac{1}{s}$  and s > 0, from the above inequality follows that

$$\lim_{\substack{n,m\to\infty}} m_b(\mu_n,\mu_m) - m_{b\mu_n,\mu_m} = 0.$$
  
Similarly, one can show  
that 
$$\lim_{n \to \infty} M_{b\mu_n,\mu_m} - m_{b\mu_n,\mu_m} = 0.$$

Thus,  $\{\mu_n\}$  is an  $M_b$ -Cauchy sequence in  $\varphi$ .

Since  $\varphi$  is complete there exist  $u \in \varphi$  such that  $\lim_{n \to \infty} m_b(\mu_n, u) - m_{b_{\mu_n, u}} = 0.$ 

Next, we prove that *u* is a fixed point of  $\xi$ . For any n > 0, we have  $\lim_{n \to \infty} m_b(\mu_n, u) - m_{b_{\mu_n,u}} = 0$ 

$$= \lim_{n \to \infty} m_b(\mu_{n+1}, u) - m_{b_{\mu_{n+1}, u}}$$
$$= \lim_{n \to \infty} m_b(\xi \mu_n, u) - m_{b_{\xi \mu_n, u}}$$
$$= m_b(\xi u, u) - m_{b_{\xi u, u}}$$

which implies that  $m_b(\xi u, u) - m_{b\xi u, u} = 0$ , hence  $m_b(\xi u, u) = m_{b\xi u, u}$ , therefore  $\xi u = u$ . Thus, u is a fixed point of  $\xi$ . Now, we show that if u is a fixed point, then  $m_b(u, u) = 0$ , assume that u is a fixed point of  $\xi$ ,

hence 
$$m_b(u, u) = m_b(\xi u, \xi u)$$

$$\gamma m_b(u,\xi u)$$

 $+\alpha m_{\rm b}(u,u)$ 

$$= (\alpha + \beta + \gamma) \quad m_b(u, u)$$

$$= \alpha + \beta + \gamma < \frac{1}{s},$$

$$\Rightarrow m_b(u, u)$$

$$= 0$$

To prove uniqueness, assume that  $\xi$  has two fixed points say  $u, v \in \varphi$ .

Hence 
$$m_b(u, v) = m_b(\xi u, \xi v)$$
  
 $\leq \alpha m_b(u, v) + \beta m_b(u, \xi u) + \gamma m_b(v, \xi v)$ 

 $\alpha m_b(u,v) + \beta m_b(u,u) +$ 

 $\leq \alpha m_h(u, u) + \beta m_h(u, \xi u) +$ 

 $= (\beta + \gamma) m_{b}(u, \xi u)$ 

 $\gamma m_h(v,v)$ 

 $\leq \alpha m_b(u, v) \\ < m_b(u, v)$ 

which implies that  $m_b(u, v) = 0$  and thus u = v.

**Corollary 4.2** Let  $(\varphi, m_b)$  be a complete  $M_b$ metric space with  $s \ge 1$  an  $\xi: \varphi \to \varphi$  satisfying the condition:

(4.2)  $m_b(\xi\mu,\xi\sigma) \le km_b(\mu,\sigma)$ 

 $\forall \mu, \sigma \in \varphi$ , where  $k \ge 0$ , with  $k < \frac{1}{s}$ , then  $\xi$  has a unique fixed point u such that  $m_h(u, u) = 0$ .

**Example 4.3.** Let  $\varphi = [0, \infty)$  and  $m_b: \varphi \times \varphi \to R$  be defined by  $m_b(\mu, \sigma) = |\mu - \sigma|^2 + \left(\frac{\mu + \sigma}{2}\right)^2$ . Then  $(\varphi, m_b)$  is a complete  $M_b$ -metric space with s = 2. Define  $\xi: \varphi \to \varphi$  by  $\xi\mu = \frac{\mu}{3}, \forall \mu \in \varphi$ .

$$m_{b}(\xi\mu,\xi\sigma) = |\xi\mu - \xi\sigma|^{2} + \left(\frac{\xi\mu + \xi\sigma}{2}\right)^{2}$$
$$= \left|\frac{\mu}{3} - \frac{\sigma}{3}\right|^{2} + \left(\frac{\frac{\mu}{3} + \frac{\sigma}{3}}{2}\right)^{2}$$
$$= \frac{1}{3^{2}}|\mu - \sigma|^{2} + \frac{1}{3^{2}}\left(\frac{\mu + \sigma}{2}\right)^{2}$$
$$= \frac{1}{3^{2}}\left[|\mu - \sigma|^{2} + \left(\frac{\mu + \sigma}{2}\right)^{2}\right]$$
$$= \frac{1}{9}m_{b}(\mu,\sigma).$$

Thus, all the conditions of Corollary 4.2 are satisfied with  $k = \frac{1}{2}$ . Hence  $\xi$  has a fixed point  $\mu =$ 0 and  $m_b(0, 0) = 0$ .

#### 5. Application

In this section, we endeavour to apply Theorem 4.1 to investigate the existence and uniqueness of solution of the Fredholm integral equation.

Consider the following integral equation:

 $\mu(t) = \int_0^{\xi} G((t, s, \mu(t))) ds,$ (5.1)

for  $t, s \in [0, \xi]$ , where  $\xi > 0$  and  $G: [0, \xi] \times$  $[0,\xi] \times R \to R$ . In this section, we present the existence theorem for (5.1). Let  $\varphi = C[0,\xi]$ be the set of continuous real functions defined on  $[0, \xi]$ . We endow  $\varphi$  with the  $M_b$ -metric

$$m_b(\mu(t), \sigma(t)) = \sup_{t \in [0,T]} \left(\frac{\mu(t) + \sigma(t)}{4}\right)^2, \text{ for all}$$
$$\mu, \sigma \in \varphi.$$

with the constant s = 2.

fixed point of f. Now, we prove the following result. work has been done.

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**Theorem 5.1:** Assume that for all  $\mu, \sigma \in$  $C[0,\xi]$ 

(5.2) 
$$|G(t,s,\mu(t)) + G(t,s,\sigma(t))| \le \lambda^{\frac{1}{2}} |\mu(t) + \sigma(t)|$$

for all  $t, s \in [0, \xi]$  where  $0 < \lambda < \frac{1}{s}$ . Then the integral equation (5.1) admits a unique solution in  $\mu \in \varphi$ .

**Proof.** From (5.2), for all 
$$t \in [0, \xi]$$
, we have  
 $m_b(\xi\mu(t), \xi\sigma(t)) = \left(\frac{\xi\mu(t) + \xi\sigma(t)}{4}\right)^2$   
 $= \left|\int_0^{\xi} \left(\frac{K(t,s,\mu(t)) + K(t,s,\sigma(t))}{4}\right) ds\right|^2$   
 $\leq \int_0^{\xi} \left|\left(\frac{K(t,s,\mu(t)) + K(t,s,\sigma(t))}{4}\right)\right|^2 ds$   
 $\leq \int_0^{\xi} \left\{\lambda^{\frac{1}{2}} \left|\left(\frac{\mu(t) + \sigma(t)}{4}\right)\right|\right\}^2 ds$   
 $\leq \lambda \int_0^{\xi} \left\{\left(\frac{|\mu(t)| + |\sigma(t)|}{4}\right)^2\right\} ds$   
 $\leq \lambda m_b(\mu(t), \sigma(t)).$ 

Thus, condition (5.1) is satisfied. Therefore, all conditions of Theorem 4.1 are satisfied. Hence  $\xi$ has a unique fixed point, which means that the Fredholm integral equation (5.3) has a unique solution. This completes the proof.

Open Problems: Prove analogue of Reich contraction, Ciric contraction and Hardy-Rogers contraction in  $M_b$ -metric space.

Acknowledgement: The authors are thankful to Then  $(\varphi, m_b)$  is a complete  $M_b$ -metric space M.P. Council of Science and Technology, for support under а Major Research Project No. Let  $f(\mu(t)) = \int_0^{\xi} G(t, s, \mu(t)) ds$  for all  $\mu \in \varphi$  3839/CST/R&D/Phy. & Engg. And Pharmacy/2023, and for all  $t, s \in [0, \xi]$ . Then the existence of a entitled "A Study of Existence of some new type of solution to (5.1) is equivalent to the existence of a Metric spaces with applications," under which this

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